

GPU Computing with CUDA

Lab 6 - Cusp

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Objectives

- ▶ Experiment with Cusp
- ▶ Outline
 - Implement a Finite Difference solution of Poisson equation
 - ▶ Try different
 - Solvers
 - Preconditioners
 - Memory spaces
 - Implement a sparse matrix vector with CSR and ELL

Cusp - Poisson problem

- ▶ See end of lecture 7 for details in derivation of the Poisson problem in FD
- ▶ Solvers:
 - GMRES, CG, BiCG-stab
- ▶ Preconditioners
 - Nothing, diagonal, smoothed aggregation
- ▶ Memory spaces
 - Host, device
- ▶ Use monitors!

Cusp - Poisson problem

```
// Generate matrix
cusp::coo_matrix<int, float, cusp::host_memory> A;
cusp::gallery::poisson5pt(A, N-2, N-2);

// Generate RHS, solution vector, and analytical solution
cusp::array1d<float, cusp::host_memory> b(A.num_rows, 1.0f);
cusp::array1d<float, cusp::host_memory> u(A.num_rows, 0);
cusp::array1d<float, cusp::host_memory> u_an(A.num_rows, 0);

for (int j=1; j<N-1; j++)
{
    for (int i=1; i<N-1; i++)
    {
        b[(j-1)*(N-2)+(i-1)] = 8*M_PI*M_PI*sin(2*M_PI*x[j*N
+i])*sin(2*M_PI*y[j*N+i])*h*h;
        u_an[(j-1)*(N-2)+(i-1)] = sin(2*M_PI*x[j*N+i])*sin(2*M_PI*y[j*N+i])
+ 1.0f;
        if ((j==1) || (j==N-2))
        {
            b[(j-1)*(N-2)+(i-1)] += 1.0f;
        }
        if ((i==1) || (i==N-2))
        {
            b[(j-1)*(N-2)+(i-1)] += 1.0f;
        }
    }
}
```

Cusp - Sparse matrix vector

- ▶ Do a sparse matrix vector product with CSR and ELL

- CSR

1	7	0	0	0	2	4	7	9	row offsets
0	2	8	0	0	1	1	2	0	column indices
5	0	3	9	1	7	2	8	5	values
0	6	0	4	3	9	6	4		

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Cusp - Sparse matrix vector

```
float *c_d;
cudaMalloc( (void**) &c_d, N_side*sizeof(float));
thrust::device_ptr<float> c_ptr(c_d);

... //do something on c_d

cusp::array1d<float, cusp::device_memory> c(c_ptr, c_ptr+N_side);

// array2d from ell comes in column major, need to transpose
// before flatten as raw pointer cast of array2d assumes row major
cusp::array2d <float, cusp::device_memory> At_val;
cusp::transpose(A.values, At_val);

float *val_d = thrust::raw_pointer_cast(&At_val(0,0));
```