

The Master of Science in Robotics and Autonomous Systems: Non-Thesis Program Planning Sheet



Student Name: _____

BU ID# _____

Email Address: _____

Advisor Name: _____

Expected Graduation Date: _____

1) Core Course Requirement - 4 credits

<u>Course #</u>	<u>Course Name</u>	<u>Credits</u>	<u>Semester/Year</u>	<u>Grade</u>
EK 505 A1	Introduction to Robotics and Autonomous Systems	4	Fall _____	_____

2) Robotics Core Requirement - 16 credits

<u>Area</u>	<u>Course #</u>	<u>Course Name</u>	<u>Credits</u>	<u>Semester/Year</u>	<u>Grade</u>
<u>C</u>	_____	_____	_____	_____	_____
<u>D</u>	_____	_____	_____	_____	_____
<u>P</u>	_____	_____	_____	_____	_____
<u>ML</u>	_____	_____	_____	_____	_____

3) Technical Elective Requirement - 12 credits

<u>Course #</u>	<u>Course Name</u>	<u>Credits</u>	<u>Semester/Year</u>	<u>Grade</u>
_____	_____	_____	_____	_____
_____	_____	_____	_____	_____
_____	_____	_____	_____	_____

4) Practicum

<u>Placement</u>	<u>Semester/Year</u>
_____	_____

Approved By:

Advisor Signature

Date

Student Signature

Date

The Master of Science in Robotics & Autonomous Systems Curricular Requirements

The program requires 32 credit hours at the 500-level or above. At least 24 credits must be taken at Boston University. To graduate, a cumulative grade point average of at least 3.0 (B) must be attained.

If necessary, students can take more than 32 credits and drop the lowest grade(s). Grades of C- or lower are not acceptable for master's degrees under any circumstance. Successful completion of a 3-credit course in either the College of Arts and Sciences or the Questrom School of Business does not obviate the need to complete 32 credits. Students are permitted to take a single course multiple times to achieve the GPA requirement, but will only receive 4 credits if used against the degree requirements.

1. Core Course Requirement (4 credits)

All students are required to take and pass ENG EK505 A1 (*Introduction to Robotics and Autonomous Systems*) in order to receive their Master's degree. This course covers the fundamentals that will be built upon in the robotics core requirements.

2. Robotics Core Requirement (16 credits)

Students must choose a course from the list below in each of the four areas of Control (C), Perception (P), Design (D), and Machine Learning (ML). Each selected course can only satisfy one core area. Note that not every course is offered every year.

Course Number	Course Name	Area
ENG ME 762 ²	Nonlinear Systems and Control	C
ENG ME 570	Robot Motion Planning	C,P
ENG ME/SE 740	Vision, Robotics, and Planning	C, P
ENG ME/SE/EC 701 ³	Optimal and Robust Control	C
ENG ME 501	Dynamic Systems Theory	C
CAS CS 585	Image and Video Computing	P
ENG EC 535	Introduction to Embedded Systems	D
ENG EC 545	Cyberphysical Systems	D
ENG ME 571	Medical Robotics	D
ENG ME 568	Soft Robotics	D
ENG ME 560	Precision Machine Design and Instrumentation	D
ENG EC 503 ¹	Learning from Data	ML
CAS CS 542	Machine Learning	ML
ENG EC 523	Deep Learning	ML
CAS CS 541	Applied Machine Learning	ML
ENG EC 518	Robot Learning	ML, P

¹If interested in the cybersecurity specialization, you must take EC 503 for ML requirement

²If interested in taking ME 762 it is highly advised that you take ME 501 prior

³Although ME 501 is a pre-req for ME 701 students with a knowledge of Ordinary Differential Equations at the level of an undergraduate degree in engineering or the physical sciences. Signals and systems or classical (undergrad level) control. State space control helpful but not required.

Optional courses to help further develop coding skills (can be counted towards technical electives):

ENG EC602: Design by Software

ENG EC504: Advanced Data Structures

ENG EC530: Software Engineering Principles

3. Technical Elective Requirement (12 credits)

Each student must complete three graduate-level courses in engineering, math, or the physical sciences to fulfill this Requirement. These courses may be taken in any department or division of the College of Engineering or in the College of Arts and Sciences and include those on the list above of robotics core (if not used to satisfy a core requirement). Students can also take and petition for an Independent Study to fulfill this requirement. The advisor must approve the three courses used to fulfill this requirement.

4. Practicum Requirement

The practicum must be satisfied (usually during the summer term) through one of the following mechanisms:

1. An industrial internship with a placement through the MS in Robotics and Autonomous Systems program
2. An independently arranged industrial internship with prior approval of the program
3. A research internship in the lab of a participating faculty member

Regardless of the mechanism, the internship must consist of at least 360 hours of effort.