ME/MS 507 Process Modelling and Control Spring 2022

Prof Gevelber, Mechanical Engineering

Office: 15 St. Mary's St., room 134. gevelber@bu.edu, W 617-353-9693,

Office Hours: by appointment. Please take advantage to ask questions, that's what I'm here for. Easy to arrange a zoom meeting.

Course Goal: This course provides an integrated study of physical system dynamics, control concepts, and process design. The goal is to deepen student's physical intuition as well as learning how to determine the appropriate roles for changing the system design and adding closed loop control. Case studies are used to examine the opportunities for developing new process capabilities and products. Examples are drawn from a variety of applications including welding, MEMS, CD manufacturing, thermal processing, film deposition for electronics, optics, energy applications, robotics, biomedical applications and high speed machining.

Requirements and Grading

Homework (20%). Typically due on Wednesday. Solutions will be posted, so late home works will not be accepted [unless medical or other excuse]. **Please bring questions to class on Mondays!** While you can discuss problems and class material with other students, your homework write up should be your own.

Two quizzes (20% each) and take-home at the end of term (35%)

Project (5%)

Project: I'm looking for you to analyze a process you choose from the perspective of the course. (Teams of two are acceptable.) Ideally, it will be a process that can yield a significant competitive advantage if developed and/or improved. However, working on something that you are familiar with is acceptable. I will be glad to discuss options.

Your project should include a description of the processing objectives/performance benchmarks, important process physics/dynamics, control objectives, design options, and possible control strategies. Detailed analysis of the system is not required (i.e. this should be descriptive and not quantitative). A one paragraph outline of your project is due the 5th session. You will present your project the last 2 classes of the term. This is a chance to reinforce the relevance of the course to your own work.

You must provide an extended outline, including sources by the 14th class.

Matlab will be used to assist in dynamic simulations, controls analysis, processing, linear algebra, and graphics (it also has other great tools/applications).

Texts:

Introduction to Physical System Dynamics, R. Rosenberg and D. Karnopp, McGraw Hill, 1983. (RK)

Notes from N. Hogan and M. Athans (to be supplied in class).

<u>Control Text:</u> you should have a intro control text such as

Control System Design and Simulation, J. Golten and A. Verwer.

Modern Control Engineering, K. Ogata, Prentice-Hall: The bible, has worked problems.

Feedback Control of Dynamic Systems, G.F. Franklin, et.al., Addison-Wesley: Nice treatment of mechanical systems for both classical and some modern approach

Feedback Control Systems, Phillips & Harbor, Prentice Hall.

Automatic Control Systems, B. C. Kuo, Prentice Hall. Verbose, but has it all.

<u>Class</u>	<u>Date</u>	<u>Topic</u>	Notes	<u>Homeworks</u>
1	24-Jan	Intro/Overview		
2	26-Jan	Control Overview & Bond Graph Intro	HP discuss	
3	31-Jan	Mech-Elec Syst	Minds Eye discuss	
4	2-Feb		Pilkington Case	Hmk 1 due
5	7-Feb	Equation Derivation	Project outline due	
6	9-Feb			Hmk 2 due
7	14-Feb	Fluid-Thermal syst		
8	16-Feb			Hmk 3 due
9	22-Feb	Applications	Case Study	
10	23-Feb			Hmk 4 due
11	28-Feb	Intro Dynamics		
12	2-Mar	Quiz 1: modeling		
		Spring Break 3/7-13		
13	Mar-14	SS to TF	Ext. Proj Outline	
14	16-Mar			Hmk 5 due
15	21 Mar	Phys Syst Dynamics		
16	23-Mar			Hmk 6 due
17	28-Mar	Frequency Domain		
18	30-Mar	JHT/accel ex		Hmk 7 due
19	4-Apr	Rel. freq. To time.		Hmk 8 due
20	6-Apr			
21	11-Apr	Control Intro		
22	13-Apr	Quiz 2: dynamics & control		
23	20-Apr	CL freq anal/design		
24	25-Apr	Actuator selection		Hmk 9 due
25	27-Apr		Take-home out	
26	2-May			Hmk 10&11
27	4-May	P26jeqtrPresentations	Project Presentati	ons
		Finals (5/9-5/13)	Take-home due 5/8 5pm	