EDUCATION	<u>11</u>	
University of California Berkeley, Berkeley, California M.Eng. in Mechanical Engineering(Cumulative GPA: 3.53 /4.0)	Aug. 2023 -	– May. 2024
• Courses: Control and Dynamics of Unmanned Aerial Vehicles, Advanced Control Systems, Capstor <b>University of California Los Angles, Los Angeles, California</b> B.S. in Physics ( <i>Cumulative GPA:3.58 /4.0</i> )	one Project-Jet Sept. 2020	Bot – Mar. 2023
• Courses: Quantum & Static Mechanics, Analytic Mechanics, Thermodynamics, Machine Learning <b>Foothill College, Los Altos, California</b> A.S. in mathematics for transfer <i>(Cumulative GPA:3.75 /4.0)</i>	, Math Metho Sept. 2017	ds-Physics – Jun. 2020
• Courses: Linear Algebra, General Physics, OBJ-Orient Prog Method in C++, Calculus		
• Awards and Honors: Dean's List (multiple quarters), Graduation with High Honors		
PROFESSIONAL EXPERIENCE		
<b>The Royal Melbourne Institute of Technology, Melbourne, Australia</b> <i>Research Analyst Intern</i>	Aug. 2019	– Oct. 2019
• Outlined and presented the forms of radiation and the appropriate materials for detecting radiation contributing to 25% of the research knowledge base	in laboratory	collection,
• Reviewed and prepared a 15-page report on nuclear physics and directions for improving the scint Hangzhou Zhinuo Technology Co., Ltd., Hangzhou, China Software Engineer Intern	illator detector Sept. 2016	r – Dec. 2016
• Maximized the use of pattern recognition technologies in C++ programming functions		
• Assessed the suitability and compatibility of the mechanical design component with the software		
• Wrote and implemented Python code while explaining software functionality to corporate custome mechanical designs were compatible	ers and ensurin	ng that
RESEARCH EXPERIENCE		
Advanced Microscopy Application in Biophysics (3D vision), UCLA Senior Member – supervised by Professor Katsushi Arisaka	Jun. 2022	– Mar. 2023
• Built an Epi-Fluorescence Microscope to observe fluorescent beads and used MATLAB to analyze	e the point spre	ead function
• Modified a 3D printer with Python (finding and fixing code so that it could move with people's heat	ads using a VF	R headset)
• Applied the Line-Confocal Microscope theorem to build a Line-Confocal Microscope; observed ze the Labview app	ebrafish eye m	notion with
• Constructed the Transverse-Sheet Illumination Microscopy detective part and converted the design Drosophila observation	1 to actual hard	dware for
<b>Influence of Angle-of-Attack on Drag Force, ICAMAM 2022</b> Co-Author	Jul. 2021 -	– Sept. 2021
• Introduced the elements of the "T- 11" parachute and "T- 11 reserve" parachute system		
• Studied the influence of the angle of attack on the drag of the parachute system		
EXTRACURRICULAR ACTIVITIES		
Volunteer at the Lawrence Hall in Ingenuity Challenge, Berkeley, California	Jun. 2019	– Aug. 2019
• Supported participants in creating and building their projects, integrating problem-solving skills ar	nd imagination	1
• Helped facilitate hands-on activities and material preparation, ensuring readiness in all aspects <b>Engineering Club, Pujiang, China</b>	Jun. 2013	– Aug. 2016
• Developed competition projects for the club that enhanced implementation efficiency using physic	s and enginee	ring tools
• Enhanced the construction process of fixed-point robots, analyzing the battery-walking distance restraight-line walking and stopping in high-grade areas	lationship, and	d achieving
COMPETITION AWARDS		
3rd place in the California PBL Awards Programs		Mar. 2019
• 3rd place in the 2017 China Innovative Robot Competition		May. 2017
• 1st place in the competition of amateur robot skills in Pujiang County		Dec. 2015
SKILLS & OTHERS		

Qian Wu

301 Guest St Apt 539, Allston, Massachusetts | (424) 535-7735 | qianwu24@bu.com

• Languages: Native Chinese (Mandarin), Professional English

• Programming and Software: C++, Python, Matlab, Solidworks, Auto CAD, Image J, Microsoft Office

• Finite Element Analysis, Simulation and Modeling Tools, Experimental Techniques, Prototyping and 3D Printing