

Neuro-Autonomy: Neuroscience-Inspired Perception, Navigation, and Spatial Awareness for Autonomous Robots



Wednesday, November 13, 2019 - Day 1

Location: 8 Saint Mary's Street (Photonics Bldg.) Room PHO 339

8:30am-9:00am Breakfast

9:00am-9:25am Yannis Paschalidis, Boston University
Introductions and Overview

9:25am-9:50am Michael Hasselmo, Boston University
Spatiotemporal Coding of Trajectories and Environments in Cortex

9:50am-10:15am Margrit Betke, Boston University
3D Visual Tracking and Pose Estimation of Animals

10:15am-10:40am Chantal Stern, Boston University
Functional MRI Studies of Navigation in Humans

10:40am-10:55am Coffee Break

10:55am-11:20am Anthony Burkitt, University of Melbourne
Data-Driven Neural Modelling Approaches to Understanding Sensory Processing

11:20am-11:45am Ken Cheng, Macquarie University
The Antarium: A Reconstructed Visual Reality Arena

11:45am-12:10pm John Baillieul, Boston University
From C. Elegans to R. Norvegicus and Beyond: Autonomy Through Synthetic Neuromotor Systems

12:10pm-1:00pm Lunch

1:00pm-1:25pm John Leonard, Massachusetts Institute of Technology
Semantic Navigation and Spatial Awareness

1:25pm-1:50pm Michael Milford, Queensland University of Technology
Place Perception Through Bio-Mimetic Sensing and Fusing Neurally-Inspired and Deep Neural Networks

1:50pm-2:15pm Girish Nair, University of Melbourne
Information Theory in the Sense-Perceive-Act Cycle

2:15pm-3:15pm Coffee Break: Tour at the Boston University Robotics Lab

3:15pm-3:40pm William Moran & Simon Williams, University of Melbourne
Optimal Scheduling for Situation Assessment

3:40pm-4:05pm Andrey Savkin, University of New South Wales
UAV Navigation for Collision Avoidance and Following Targets

4:05pm-5:15pm Visit of the BU Center for Integrated Life Sciences and Engineering (CILSE) and Tour of the Facilities (fMRI, Rat Physiology Lab)

6:00pm Dinner: Barcelona Wine Bar (1700 Beacon St., Brookline)

www.bu.edu/cise

