

Neuro-Autonomy: Neuroscience-Inspired Perception, Navigation, and Spatial Awareness for Autonomous Robots



Wednesday, November 13, 2019 - Day 1

Location: 8 Saint Mary’s Street (Photonics Bldg.) Room PHO 339

8:30am-9:00am	Breakfast
9:00am-9:25am	Yannis Paschalidis , Boston University Introductions and Overview
9:25am-9:50am	Michael Hasselmo , Boston University Spatiotemporal Coding of Trajectories and Environments in Cortex
9:50am-10:15am	Margrit Betke , Boston University 3D Visual Tracking and Pose Estimation of Animals
10:15am-10:40am	Chantal Stern , Boston University Functional MRI Studies of Navigation in Humans
10:40am-10:55am	Coffee Break
10:55am-11:20am	Anthony Burkitt , University of Melbourne Data-Driven Neural Modelling Approaches to Understanding Sensory Processing
11:20am-11:45am	Ken Cheng , Macquarie University The Antarium: A Reconstructed Visual Reality Arena
11:45am-12:10pm	John Baillieul , Boston University From C. Elegans to R. Norvegicus and Beyond: Autonomy Through Synthetic Neuromotor Systems
12:10pm-1:00pm	Lunch
1:00pm-1:25pm	John Leonard , Massachusetts Institute of Technology Semantic Navigation and Spatial Awareness
1:25pm-1:50pm	Michael Milford , Queensland University of Technology Place Perception Through Bio-Mimetic Sensing and Fusing Neurally-Inspired and Deep Neural Networks
1:50pm-2:15pm	Girish Nair , University of Melbourne Information Theory in the Sense-Perceive-Act Cycle
2:15pm-3:15pm	Coffee Break: Tour at the Boston University Robotics Lab
3:15pm-3:40pm	William Moran & Simon Williams , University of Melbourne Optimal Scheduling for Situation Assessment
3:40pm-4:05pm	Andrey Savkin , University of New South Wales UAV Navigation for Collision Avoidance and Following Targets
4:05pm-5:15pm	Visit of the BU Center for Integrated Life Sciences and Engineering (CILSE) and Tour of the Facilities (fMRI, Rat Physiology Lab)
6:00pm	Dinner: Barcelona Wine Bar (1700 Beacon St., Brookline)

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